## Distributed Distance-Bounded Network Design Through Distributed Convex Programming OPODIS 2017

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#### Distance Bounded Network Design

- Given input graph G, find a subgraph H with minimum cost such that certain pairs of vertices are within some distance bound D of each other in H.
- A well-known class are graph spanners: the distance in H for certain pairs is within a certain factor of their original distance in G.
- Most of these problems are NP-hard so the focus is often polynomial time approximation algorithms.

#### Example of Distance Bounded Network Design

• Set of demands:  $S = \{(u, v), (w, v), (y, w)\}$ , distance bound D = 2.

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Find smallest subgraph H of G s.t, all the pairs in S are connected with a path of length at most 2.



## Distributed Linear Programming

- Solving linear programs is often challenging task in distributed settings.
- Focus has mainly been solving packing and covering linear programs in a distributed manner (e.g. Kuhn, Moscibroda, and Wattenhofer 2006).

We provide efficient distributed algorithms for distance-bounded network design LPs and a class of convex problem that generalize these problems.

- For several distance-bounded network design problems, we give approximation guarantees that match their best known centralized bounds.
- Example of these problems are: Directed k-Spanner, Basic
   3-Spanner, Basic 4-Spanner and Lowest-Degree k-Spanner.
- These algorithms run in O(Dlogn) rounds, where D is the maximum distance bound.
- This is the best known bound for these problems in the LOCAL model, and local computation is polynomial time.

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#### Communication model

#### *LOCAL* model:

- Nodes take step in synchronous rounds and in each round every node can send an arbitrary message of unbounded size to each of its neighbors in the underlying graph G = (V, E).
- Communication is bidirectional, but the input graph may be directed.

#### Related Work

- Kuhn, Moscibroda, and Wattenhofer (2006) use a Linial-Saks decomposition to solve a packing or covering LP.
- Dinitz and Krauthgamer (2011) showed how to solve the Basic 2-Spanner LP in O(log<sup>2</sup> n) rounds.

We use similar techniques based on padded decompositions.

 Barenboim, Elkin, and Gavoille (2016) showed for any integer parameters k, α, gives an O(n<sup>1/α</sup>)-approximation for Directed k-Spanner in exp(O(α)) + O(k) time.

They require heavy (exponential time) local computation.

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#### Approximation with Linear Programming

The discrete problem is modelled via an integer program of the following form:

max 
$$c^T x$$
  
s.t.  $Ax \leq b$   
 $x = \{0, 1\}^d$ 

- The problem is then relaxed into a linear program by changing each integer constraint x<sub>i</sub> = {0,1} to to 0 ≤ x<sub>i</sub> ≤ 1.
- Fractional solutions will be rounded to integers using an appropriate rounding scheme.

# Distance-Bounded Network Design Convex ProgramWe consider convex programs of the following form:

$$\begin{array}{ll} \min & g(x) \\ \text{s.t.} & \sum_{P \in \mathcal{P}_{u,v}: e \in P} f_P \leq x_e & \quad \forall (u,v) \in \mathcal{S}, \forall e \in E \\ & \sum_{P \in \mathcal{P}_{u,v}} f_P \geq 1 & \quad \forall (u,v) \in \mathcal{S} \\ & x_e \geq 0 & \quad \forall e \in E \\ & f_P \geq 0 & \quad \forall (u,v) \in \mathcal{S}, \forall P \in \mathcal{P}_{u,v} \end{array}$$

- g(x) is typically a linear function, but more generally a convex function that has a certain partitionability property.
- $\mathcal{P}_{u,v}$  is a set of allowed paths, we assume that length of these paths are bounded by D.

Solving the Distance-Bounded Network Design Convex Program

Our main result is the following:

#### Theorem

For any constant  $\epsilon > 0$ , any distance-bounded network design convex program can be solved up to a  $(1 + \epsilon)$ -approximation in  $O(D \log n)$  rounds in the  $\mathcal{LOCAL}$  model, where  $D = \max_{(u,v)\in S} \max_{P \in P_{u,v}} \ell(P).$ 

If the convex program can be solved in polynomial time in the centralized sequential setting, then the distributed algorithm uses only polynomial-time computations at every node.

#### Padded Decomposition

#### Definition

Given an *undirected* graph G, a  $(k, \epsilon)$ -padded decomposition,

where  $0 < \epsilon \le 1$ , is a probability measure  $\mu$  over the set of graph partitions (clusterings) that has the following properties:

- For every P ∈ supp(μ), and every cluster C ∈ P, we have: diam(C) ≤ O((k/ε) log n).
- For every u ∈ V, the probability that all nodes in B(u, k) are in the same cluster is at least 1 − ε.

#### Padded Decomposition

- Every cluster has low diameter of  $O((k/\epsilon) \log n)$ .
- For each node the probability that all node is k-neighborhood are in the same cluster is at least  $1 \epsilon$ .



#### High Level Idea: Partition

- Partition the graph by a distributed algorithm that samples from a (D, ε)-padded decomposition in O(<sup>D</sup>/<sub>ε</sub> ln n) rounds.
- Nodes know the center of the cluster they belong to.



## High Level Idea: Solving Local LPs

- The center of each cluster solves a local linear program.
- Cluster center broadcasts the solutions to all the nodes in the cluster.



#### High Level Idea: Putting it together

- Repeat this process  $O(\frac{\ln n}{\epsilon})$  times in *parallel* (decompositions are independent).
- For each edge taking average over local solutions for iterations in which the ball around that edge is in the same cluster will yield to a global solution.
- Using Chernoff bounds, we show that the global solution formed is feasible to the global LP and is a constant factor of the optimal solution.

## Applications

- Distance-bounded network design problems that have a local rounding can be solved.
- With high probability there is an O(n<sup>1/2</sup> ln n)-approximation to the Directed-k-spanner problem that runs in O(k log n) time in the LOCAL model.
- There is a distributed algorithm that w.h.p. computes an Õ(Δ<sup>(1-1/k)<sup>2</sup></sup>)-approximation to the Lowest-k-Degree Spanner problem, taking O(k log n) rounds of the LOCAL.

#### Thanks!

#### Questions?